Diagram detailing all aspects of the Robot:

Primary :

Software :

1. Language ( Java, C …)
2. AI (expressions )
3. Motion tracking
4. Data gathering ( best function of the robot )

Mechanical movements :

1. Joints
2. Fixed or mobile
3. Materials
4. Hardware (Servos, wheels …)
5. Design software used (solid works …)

Hardware :

1. Components (Arduino, computer …)
2. Ventilation (cooling system)

Customer Interactions :

1. Functions
2. Expressions ( face and language )

Body :

1. Shape
2. Material of outer surface
3. Software used (solid works)